# ON THE SHOCK WAVE IN A FLOW PAST A CONVEX CORNER 

PMM Vol.41, № 2, 1977, pp. 292-297<br>A. I. ESIN and I. A. CHERNOV<br>(Saratov)<br>(Received May 5, 1976)

A local problem of a subsonic gas flow past a finite convex corner is studied. Complete gasdynamic equations are used to show that a shock-free flow is impossible if a singularity develops at the corner point [1] and the wall behind the corner is rectilinear. A solution adjacent to the centered rarefaction wave downstream is found ineffective in the neighborhood of the singular characteristic emerging from the corner point. A uniformly effective solution is obtained using the method of deformed coordinates, and a shock wave is constructed.

1. Flow ahead the shock wave. Let us consider a steady plane subsonic


Fig. 1 flow past a perfect gas with the ratio of specific heats $\gamma$ assuming that the walls of the finite convex corner are rectilinear (Fig. 1). A local solution for a finite value of the corner angle $\beta$ in the region $A O C$ is known $[2,3]$. The problem therefore is that of constructing a solution in the region $C O D$. Without affecting the general character of the arguments that follow, we can assume that the flow to the left of the last characteristic $O C$ emerging from the corner point $O$, is potential. Then the solution [3] in the zone $B O C$ of the centered rarefaction wave can be written in the form ( $z$ is fixed) [4]

$$
\begin{align*}
& \Phi=g_{0}(z) y+g_{k}(z) y^{1+2 k / 3}, \quad y \rightarrow 0, \quad z=x / y  \tag{1.1}\\
& g_{0}=v^{-1}\left(1+z^{2}\right)^{1 / 2} \sin \omega, \quad \omega=v \operatorname{arctg} z, \quad v^{2}=(\gamma-1) / \\
& /(\gamma+1) \\
& g_{m}=(\sin \omega)^{m / 3}(\cos \omega)^{1+m / 3 v v}\left(1+z^{2}\right)^{1,2+m_{1} 3}\left[A_{m}+H_{m}(\omega)\right] \\
& H_{m}=\int(\sin \omega)^{-m / 3}(\cos \omega)^{-1-m / 3 v^{2}} E_{m}(\omega) d \omega \\
& E_{m}=-(\gamma+1)(1+2 m / 3)^{-1}(\sin 2 \omega)^{-1}\left(1+z^{2}\right)^{1 / z^{-m} / 3} G_{m}(\omega) \\
& U=u_{0}(z)+u_{k}(z) y^{2 k / 3}, \quad V=v_{0}(z)+v_{k}(z) y^{2 k k_{i} 3} \\
& u_{m}=g_{m}^{\prime}, \quad v_{m}=(1+2 m / 3) g_{m}-z g_{m}^{\prime}, \quad m=0,1, \ldots
\end{align*}
$$

Here $\Phi, U$ and $V$ are respectively the putential and the components of the velocity vector $\mathbf{w}$ along the $x$ - and $y$-axes; $k=1,2, \ldots$ denotes summation; $G_{m}$ are
functions of the previous approximations $\left(G_{1} \equiv 0\right) ; A_{m}$ are constants which are found by combining with a solution of the type given in [2]. In particular, we have

$$
A_{1}=-\frac{27}{5} C^{1 / 3}(\gamma+1)^{1 / 18}(\gamma-1)^{-1 / 4}, \quad A_{2}=0
$$

where $C$ is an arbitrary constant depending on the solution of the problem in the whole.
To simplify the boundary conditions and the solution in the region $C O D$, we pass to the rectangular $x^{\prime}-, y^{\prime}$-coordinates obtained from the $x-, y$-coordnates by rotating them through an angle $\beta$ (see Fig. 1). Then, with the angular coefficient $z_{c}$ of the characteristic $O C$ at the point $O$ known and representing a root of the equation

$$
z_{c}-g_{0}\left(z_{c}\right) / g_{0}^{\prime}\left(z_{c}\right)=\operatorname{tg} \beta
$$

we can rewrite the solution (1.1) in the form

$$
\begin{align*}
& \Phi=q_{0}^{\circ}(\xi)_{x}+q_{k}^{\circ}(\xi) x^{1+2 k / 3}, \quad x \rightarrow 0, \quad \xi=B y / x  \tag{1.2}\\
& q_{m}^{\circ}=g_{m} \eta^{1+2 m \mid 3}, \quad \eta(\xi)=\xi_{B-2} \cos \beta-\sin \beta, m=0,1, \ldots \\
& B=v^{-1} \operatorname{tg} \omega_{c}, \quad \omega_{c}=v \operatorname{arctg} z_{c}
\end{align*}
$$

(the primes are omitted). From (1.2) we obtain the equation of the characteristic $O C$ in the form

$$
\begin{equation*}
\xi=1+\xi_{k}^{0} x^{2 k \mid 3} \tag{1.3}
\end{equation*}
$$

Here

$$
\begin{align*}
& \frac{\xi_{m}^{0}}{U_{0}}=\frac{3(\gamma-1)}{m}\left(\sin 2 \omega_{c}\right)^{-2}\left[\frac{\sin 2 \omega_{c}}{\left(\gamma^{2}-1\right)^{1 / 2}} v_{m}^{0}-u_{m}^{0}\right]_{\xi=1}+e_{m}^{0}(1)  \tag{1,4}\\
& u_{m}^{0}=\left(u_{m} \cos \beta-v_{m} \sin \beta\right) \eta^{2 m / 3} \\
& v_{m}^{0}=\left(u_{m} \sin \beta+v_{m} \cos \beta\right) \eta^{2 m / 3}, \quad m=1,2, \ldots
\end{align*}
$$

where $U_{0}=u_{0}{ }^{\circ}(1)$ denotes the velocity of a homogeneous supersonic flow adjacent to the simple centered rarefaction wave, and $e_{m}{ }^{\circ}(\xi)$ are functions of the preceding approximations ( $e_{1} \equiv 0$ ).

In the first approximation the velocity potential at the characteristic $O C$ is given by

$$
\begin{equation*}
(\Phi)_{O C}=U_{0} x+q_{1}^{0}(1) x^{5_{3}}+O\left(x^{7_{1}}\right) \tag{1.5}
\end{equation*}
$$

We assume that the further extension of the flow is shock-free. Then the solution of the problem within $C O D$ must be solved with the data at the characteristic $U C$ and on the wall $O D$ (flow past condition). The solution with $x \rightarrow 0$ and fixed $\xi$ must have the form (1.5) where $q_{1}{ }^{\circ}(1)$ is replaced by $q_{1}(\xi)$ satisfying the equation

$$
\left(1-\xi^{2}\right) q_{1}^{\prime \prime}+{ }^{4} / 3 \xi q_{1}^{\prime}-10 / 8 q_{1}=0
$$

the general solution of which is

$$
\begin{equation*}
q_{1}=\Lambda_{1}(1-\xi)^{s_{1}}+\Lambda_{2}(1+\xi)^{t_{1}} \tag{1,6}
\end{equation*}
$$

where $\Lambda_{1}$ and $\Lambda_{2}$ are arbitrary constants,
From (1.6) it follows that $q_{1}{ }^{\prime \prime}(\xi) \rightarrow \infty$ as $\xi \rightarrow 1$ if only $\Lambda_{1} \neq 0$. For a rectilinear wall $O D$ the coefficient $\Lambda_{1}$ cannot be zero, consequently infinite accelerations arise on the straight line $\xi=1$ and a shock-free flow which formally exists becomes devoid of
physical sense. This was shown in $[5,6]$ for the case of $\beta \ll 1$ by studying the transonic equations.
2. Flow behind the shock wave. We shall now assume that a curved shock wave, the form of which is to be determined, serves as a boundary separating the regions $B O C$ and $C O D$. We write the conditions at the discontinuity in the form

$$
\begin{equation*}
\left[w_{\tau}\right]=0, \quad w_{n}{ }^{\circ} w_{n}=1-v^{2} w_{\tau}^{2} \tag{2.1}
\end{equation*}
$$

Here $w_{n}$ and $w_{\tau}$ are the velocity vector $w$ components normal and tangential to the discontinuity and $[X]=X-X^{\circ}$ denotes the jump in the value of $X$ during the passage through the discontinuity. As the initial system of equations we use the transformed continuity and vorticity equations

$$
\begin{align*}
& \operatorname{div}\left[\left(1-w^{2}\right)^{1 /(\gamma-1)} w\right]=0  \tag{2.2}\\
& \operatorname{rot}\left[\frac{w \times \operatorname{rot} w}{1-w^{2}}\right]=0
\end{align*}
$$

Analyzing the first boundary condition of (2.1) we find that the solution of (2.2) should be sought in the form

$$
\begin{equation*}
u=U_{0}+u_{k}(\xi) x^{2 k / 3}, \quad v=v_{k}(\xi) x^{2 k / 3} \tag{2.3}
\end{equation*}
$$

where $u$ and $v$ are components of the velocity vector along the axes of the new coordinate system. According to the flow past condition we have

$$
v_{m}(0)=0, \quad m=1,2, \ldots
$$

From the first condition of (2.1) and from (2.3) it follows directly that the shock intensity at the corner apex is zero. The coefficients $u_{m}$ and $v_{m}(m=1,2, \ldots)$ satisfy the following system of ordinary differential equations:

$$
\begin{aligned}
& v_{m}^{\prime}-B\left(2 / s m u_{m}-\xi u_{m}^{\prime}\right)=B F_{m}(\xi) \\
& 2 / s m v_{m}-\xi v_{m}^{\prime}-B u_{m}^{\prime} \Rightarrow B P_{m}(\xi)
\end{aligned}
$$

where $F_{m}$ and $P_{m}$ are functions of the preceding approximations $F_{1}=P_{1}=P_{2} \equiv$ 0 ). Assuming that

$$
\begin{align*}
& u_{m}=\left(1+\frac{2}{3}!m\right) q_{m}(\xi)-\xi q_{m}^{\prime}(\xi)-\int_{0}^{\xi} P_{m}(\xi) d \xi  \tag{2.4}\\
& v_{m}=B{q_{m}^{\prime}}^{\prime}(\xi)
\end{align*}
$$

we obtain the following equation for determining $q_{m}$ :

$$
\begin{align*}
& \left(1-\xi^{2}\right) q_{m}^{\prime \prime}+\frac{4}{3} m \xi q_{m}^{\prime}-\frac{2}{3} m\left(1+\frac{2}{3} m\right) q_{m}=  \tag{2.5}\\
& F_{m}+\xi P_{m}-\frac{2}{3} m \int_{0}^{\xi} P_{m}(\xi) d \xi
\end{align*}
$$

The general solution of the homogeneous equation corresponding to (2.5) has the form

$$
q_{m}(\xi)=\Lambda_{1 m}(1-\xi)^{1+2 m / 3}+\Lambda_{2 m}(1+\xi)^{1+2 m / 3}
$$

Knowing this solution we can write the general solution of (2.5). After satisfying the flow past condition, we obtain

$$
\begin{align*}
& q_{1} / U_{0}=C_{1}\left(\lambda^{1 / 2}+\mu^{5 / 2}\right), \quad \lambda=1-\xi, \quad \mu=1+\xi  \tag{2,6}\\
& q_{2} / U_{0}=C_{2}\left(\lambda^{1 / s}+\mu^{7 / s}\right)+a_{k} \lambda^{(k+1) / 3} \mu^{(6-k) / 3}, \quad k=1,2,3,4  \tag{2.7}\\
& a_{1}=a_{4}=-5 /{ }_{12}\left[\gamma+1+(\gamma-3) B^{2}\right] D C_{1} \\
& a_{2}=a_{3}=-{ }^{25} / 72(\gamma+1) M^{2} D C_{1} \\
& D=M^{2} C_{1} / B^{2}, \quad M^{2}=1+B^{2} \\
& q_{3} / U_{0}=C_{3}\left(\lambda^{3}+\mu^{3}\right)-9 / 10 c\left(\lambda^{-1 / 4} \mu^{10 / 3}+\lambda^{10 / 3} \mu^{-1 / 5}\right)+  \tag{2,8}\\
& b_{k} \lambda^{k / 3} \mu^{(9-k) / 3}, \quad k=1,2, \ldots, 8 ; \quad P_{3}(\xi)=2 C_{\Delta} \xi \\
& c=-2 / 9 a_{1}{ }^{2} / C_{1}, \quad b_{1}=b_{8}=4 / 5 a_{1} a_{2} / C_{1} \\
& b_{2}=b_{7}=-\frac{D}{56}\left\{-\frac{56 a_{1} C_{2}}{D C_{1}}+\frac{10}{3}\left[17(\gamma+1)-(3 \gamma+11) B^{2}\right] a_{1}+\right. \\
& \left.10(\gamma+1) M^{2} a_{2}+\frac{125}{9}\left[\gamma+1+2(\gamma-3) B^{2}+(\gamma+1) B^{4}\right] C_{1}^{2}\right\} \\
& b_{3}=b_{6}=-\frac{5 D}{72}\left\{14(\gamma+1) M^{2} C_{2}+2\left[7(\gamma+1)-(\gamma-3) B^{2}\right] a_{2}+\right. \\
& \left.\frac{25}{9}(\gamma+1) M^{4} C_{1}{ }^{2}\right\} \\
& b_{4}=b_{5}=-\frac{D}{40}\left\{-\frac{56 a_{1} C_{2}}{D C_{1}}+\frac{25}{3}(\gamma+1)\left(5+B^{2}\right) a_{1}+\right. \\
& \left.\frac{40}{3}\left[2(\gamma+1)+\gamma B^{2}\right] a_{2}+\frac{125}{9}(\gamma+1)\left(1-B^{4}\right) C_{1}{ }^{2}\right\}
\end{align*}
$$

The constants $C_{1}, C_{2}, C_{3}$ and $C_{6}$ appearing in (2.4), (2.6)-(2.8) are found from the conditions at the discontinuity.

The solution (2.3) does not hold in the region where $\lambda \sim x^{2}$. This is explained by the fact that $q_{2}{ }^{\prime}(\xi), q_{3}(\xi) \rightarrow \infty$ for $\xi \rightarrow 1$ and the conditions at the discontinuity can no longer be met. The accumulation of singularities in the solution (2.3) can be prevented by deforming the coordinates $[7,8]$. To do this we write the required solution in the parameteric form

$$
\begin{align*}
& u=U_{0}+U_{k}(s) x^{2 k / 3}, \quad v=V_{k}(s) x^{2 k / 3}  \tag{2.9}\\
& \xi=s+\xi_{k}(s) x^{2 k / 3}
\end{align*}
$$

where the coefficients $U_{k}, V_{k}$ and the deformation $\xi_{k}$ are to be determined. The value of the parameter $s=1$ corresponds to the special characteristic $O C^{\prime}$, which is the only characteristic in the region $C^{\prime} O D$ which emerges from the corner point and moves to the left [9]. To find the solution in the form (2.9), we introduce an auxilliary function which is a velocity potential in an irrotational flow past the corner

$$
\begin{equation*}
\Phi=U_{0} x+q_{1}(\xi) x^{3 / 2}+q_{2}(\xi) x^{7 / 2}+q_{3}(\xi) x^{3}+O\left(x^{12 / 2}\right) \tag{2.10}
\end{equation*}
$$

where the coefficients are given by the formulas (2.6) - (2.8). Using (2.10) we can write the solution (2.3) in the form

$$
u=\Phi_{x}-B^{2} C_{\Delta} y^{2}, \quad v=\Phi_{y}
$$

and from this we conclude that the parametrization of ( 2.9 L is equivalent to representing the function $\Phi$ in the form

$$
\Phi=U_{0} x+Q_{1}(s) x^{2 / 2}+Q_{2}(s) x^{2 / 2}+Q_{8}(s) x^{3}+O\left(x^{11 / 4}\right)
$$

$$
\xi=s+\xi_{1}(s) x^{3 / 3}+\xi_{2}(s) x^{4 / s}+O\left(x^{2}\right)
$$

Carrying out the re-expansion of the functions (2.10) as given by the method in [8] we find, that $Q_{1}, Q_{2}$ and $Q_{3}$ are determined by the formulas (2.6)-(2.8) in which $\xi$ is replaced by $s$, and the right-hand sides of the first equations in (2.7), (2.8) complemented by the equations containing the deformations, namely

$$
\xi_{1} Q_{1}^{\prime} / U_{0}, \quad\left(\xi_{1} Q_{2}^{\prime}+\xi_{2} Q_{1}^{\prime}-1 / \xi_{2}^{2}{ }_{1} Q_{1}{ }^{\prime \prime}\right) / U_{0}
$$

Requiring that $Q_{2}{ }^{\prime}$ and $Q_{3}{ }^{\prime}$ be bounded when $s=1$, we find

$$
\xi_{1}={ }^{3 / 5} 2^{5 / 5} a_{1} / C_{1}, \quad \xi_{2}=3 / 52^{7 / 4} b_{2} / C_{1}
$$

All subsequent deformations can also be chosen as constants. In general we have

$$
\begin{equation*}
\frac{\xi_{m}}{U_{0}}=\frac{6(\gamma-1)}{2 m+3}\left(\sin 2 \omega_{c}\right)^{-2}\left[\frac{\sin 2 \omega_{\mathrm{c}}}{\left(\gamma^{2}-1\right)^{1 / 2}} V_{m}-U_{m}\right]_{s=1}+e_{m}(1) \tag{2.11}
\end{equation*}
$$

where $e_{m}(s)$ are functions of the preceding approximations ( $e_{1} \equiv 0$ ). The coefficients $U_{m}$ and $V_{m}$ of the expansions (2.9) have the following form for $m=1,2,3$ :

$$
\begin{aligned}
& U_{1}=5 / 3 Q_{1}-s Q_{1}^{\prime}, \quad U_{2}=7 / 3 Q_{2}-s Q_{2}^{\prime}-{ }^{5} / 3 \xi_{1} Q_{1}^{\prime} \\
& U_{3}=3 Q_{3}-s Q_{3}^{\prime}-5 / 3 \xi_{1} Q_{2}^{\prime}-{ }^{7} / 3 \xi_{2} Q_{1}^{\prime}-C_{4} s^{2}, \quad V_{m}^{\prime}=B Q_{m}^{\prime}
\end{aligned}
$$

We can check by direct substitution that the flow past conditions of the wall $O U$ hold

$$
\begin{aligned}
& V_{1}(0)=0, \quad V_{2}(0)=\xi_{1} V_{1}^{\prime}(0) \\
& V_{3}(0)=\xi_{1} V_{2}^{\prime}(0)+\xi_{2} V_{1}^{\prime}(0)-1 / 2 \xi_{1}^{2} V_{1}^{n}(0)
\end{aligned}
$$

We assume that the equation of discontinuity has the form

$$
\begin{aligned}
& \xi=1+\xi_{1} x^{2 / 3}+\xi_{2}{ }^{0} x^{4 / 3}+\delta_{3} x^{2}+O\left(x^{1 / 3}\right) \\
& \left(\lambda=-s_{3} x^{2}+O\left(x^{0 / 2}\right)\right)
\end{aligned}
$$

The coefficients $\xi_{1}{ }^{\circ}, \xi_{2}{ }^{\circ}$ are found using (1.4). The unknowns $\delta_{3}$ and $s_{3}$ are connected by the following relation:

$$
\begin{equation*}
\delta_{3}-s_{3}=\xi_{3} \tag{2.12}
\end{equation*}
$$

The difference between the discontinuity and the characteristic is described by the coefficient $s_{3} ; \xi_{3}$ denotes a third order deformation although it should not be obtained by studying the fourth order approximation since $\xi_{s}$ represents, on the other hand, a coefficient of the special characterisitc computed from the third approximation. Taking into account the conditions (2.1), we find from (1.4) and (2.11), as was to be expected, that $\xi_{1}=\xi_{1}{ }^{\circ}, \xi_{2}=\xi_{2}{ }^{\circ}$.

The second condition of (2.1) is satisfied identically in the first and second approximation, while in the third approximation it yields

$$
\begin{align*}
& \delta_{3}=\xi_{3}{ }^{\circ}-{ }^{3} / 2_{2} s_{3}-5 / 1{ }_{12} A s_{3}{ }^{2 / 3}-{ }^{25} / 108  \tag{2.13}\\
& A^{2} s_{3}^{1 / 2} \\
& A=\frac{(\gamma+1) M^{4}}{B^{2}} C_{1}
\end{align*}
$$

Setting $s_{3}=K^{3} A^{3} / 27$, we reduce the system (2.12),(2.13) to a single equation

$$
K^{3}+\frac{1}{2} K^{2}+\frac{5}{6} K+\frac{54}{5} \frac{\xi_{3}-\xi_{3}{ }^{0}}{A^{3}}=0
$$

which has a single positive real root. For $\beta \ll 1$ the above equation becomes

$$
K^{3}+1 / 2 K^{2}+5 / 6 K-{ }_{6}^{25 / 36}=0
$$

with the approximate value of the root $K=0.5132$.
The constants $C_{1}$ and $C_{4}$ are found in the form

$$
C_{1}=U_{0}^{2 / 3}\left[2 g_{0}\left(z_{c}\right)\right]^{-5 / 0} g_{1}\left(z_{c}\right), \quad C_{4}=0
$$

Since $C_{1}<0$, we also have $s_{3}<0$. Then from (2.13) it follows that the discontinuity lies on the left of the characterisitc $O C$. This was shown from the case $\beta \ll 1$ in [6] using the transonic equations. It can be directly established that the velocity behind the shock is supersonic, and we have

$$
\frac{\left[w_{n}\right]}{w_{n}^{\circ}}=-\frac{8 B^{2}}{(\gamma+1) M^{2}}\left(\delta_{3}-\xi_{3}{ }^{\circ}\right) x^{2}+O\left(x^{1 / 2}\right)
$$

Since the coefficient in front of $x^{2}$ is negative, it follows that the discontinuity constructed is a shock wave.

The authors thank S. V. Fal' kovich for valuable comments.

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